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### Optimal Runge-Kutta Schemes for High-order Spatial and Temporal Discretizations



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> 2015 AIAA SciTech June 23, 2015



### **Outline**



- Introduction
- Governing Equations
  - Spatial Discretizations
  - Temporal Discretizations
- Von Neumann Analysis (VNA)
- Computational Results
  - One-dimensional Wave
  - Three-dimensional Vortex
- Conclusions and Future Work



### Introduction



- High-order in space is now commonplace
- High-order in time... not so much...
- Is this sufficient? Is high-order in time needed?
- <u>Limiting Fact:</u> There are no A-stable backward-difference formula (BDF) methods with > 2<sup>nd</sup> -order accuracy
- Thus, multistage methods, like Runge-Kutta (RK) methods, must be used for 3<sup>rd</sup>- and higher-order
- Explicit RK methods are not amenable to stiff problems

Objective: To find optimal diagonally-implicit Runge-Kutta time integrators for use with high-order spatial discretizations



# **Governing Equations**



#### Dual Time Stepping:

$$\frac{\partial \mathbf{Q}}{\partial \tau} + \frac{\partial \mathbf{Q}}{\partial t} + \frac{\partial \mathbf{F}_i}{\partial x_i} = \frac{\partial \mathbf{V}_i}{\partial x_i} + \mathbf{H} \qquad \mathbf{Q} = \begin{bmatrix} \rho & \rho u_i & \rho e_0 \end{bmatrix}^T$$

$$\mathbf{F}_i = \begin{bmatrix} \rho u_i & \rho u_i u_j + p \delta_{ij} & u_i \rho h_0 \end{bmatrix}^T \text{ where } h_0 = e_0 + \frac{p}{\rho}$$

#### Quasi-linear Form:

$$\frac{\partial \mathbf{Q}}{\partial \tau} + \frac{\partial \mathbf{Q}}{\partial t} + \underline{\mathbf{A}} \frac{\partial \mathbf{Q}}{\partial x_i} = \frac{\partial \mathbf{V}_i}{\partial x_i} + \mathbf{H} \qquad \underline{\mathbf{A}} = \frac{\partial \mathbf{F}_i}{\partial \mathbf{Q}} = \underline{\mathbf{M}} \underline{\mathbf{\Lambda}} \underline{\mathbf{M}}^{-1}$$

$$\underline{\mathbf{\Lambda}} = diag \{ u_i + c, u_i, u_i - c \}$$

#### Residual Form:

$$\frac{\partial \mathbf{Q}}{\partial \tau} + \frac{\partial \mathbf{Q}}{\partial t} + \mathbf{R}_s \left( \mathbf{Q} \right) = 0 \quad where \quad \mathbf{R}_s = \frac{\partial \mathbf{F}_i}{\partial x_i} - \frac{\partial \mathbf{V}_i}{\partial x_i} - \mathbf{H}$$



# **Spatial Discretizations**



- Central Differences with added artificial dissipation
- Central differences:

$$\left. \frac{\partial \Upsilon_j}{\partial x_i} \right|_{II} = \frac{\Upsilon_{j+1} - \Upsilon_{j-1}}{2\Delta x_i}$$

$$\left. \frac{\partial \Upsilon_j}{\partial x_i} \right|_{IV} = \frac{-\Upsilon_{j+2} + 8\Upsilon_{j+1} - 8\Upsilon_{j-1} + \Upsilon_{j-2}}{12\Delta x_i}$$

$$\left. \frac{\partial \Upsilon_{j}}{\partial x_{i}} \right|_{VI} = \frac{\Upsilon_{j+3} - 9\Upsilon_{j+2} + 45\Upsilon_{j+1} - 45\Upsilon_{j-1} + 9\Upsilon_{j-2} - \Upsilon_{j-3}}{60\Delta x_{i}}$$

where  $\Upsilon$  could be  $\mathbf{F}_i$  or  $\mathbf{Q}$  depending on the form of the equations

Scalar artificial dissipation:

$$\mathbf{R}_{s} = \frac{\partial \mathbf{F}_{i}}{\partial x_{i}} - \varepsilon_{\eta} \parallel \lambda \parallel \frac{\partial^{\eta} \mathbf{Q}}{\partial x_{i}^{\eta}} - \frac{\partial \mathbf{V}_{i}}{\partial x_{i}} - \mathbf{H}$$

where  $\eta$  is even and one more than the order of accuracy

$$\parallel \lambda \parallel = |u_i| + c$$
  $\varepsilon_{II} = \frac{\Delta x_i}{2}, \quad \varepsilon_{IV} = -\frac{\Delta x_i^3}{12}, \quad \varepsilon_{VI} = \frac{\Delta x_i^5}{60}.$ 



### **Temporal Discretizations**



#### **Runge-Kutta Methods:**

$$t^k = t^n + c_k \Delta t$$

$$\mathbf{Q}^k = \mathbf{Q}^n - \Delta t \sum_{j=1}^s a_{kj} \mathbf{R}_s^j(\mathbf{Q}^j) \qquad k = 1, 2, \dots, s$$

$$\mathbf{Q}^{n+1} = \mathbf{Q}^n - \Delta t \sum_{j=1}^s b_j \mathbf{R}_s^j(\mathbf{Q}^j) \qquad \qquad \hat{\mathbf{Q}}^{n+1} = \mathbf{Q}^n - \Delta t \sum_{j=1}^s \hat{b}_j \mathbf{R}_s^j(\mathbf{Q}^j)$$

$$\hat{\mathbf{Q}}^{n+1} = \mathbf{Q}^n - \Delta t \sum_{j=1}^s \hat{b}_j \mathbf{R}_s^j(\mathbf{Q}^j)$$

$$\epsilon^{n+1} = \mathbf{Q}^{n+1} - \hat{\mathbf{Q}}^{n+1}$$



### **ESDIRK Methods**



- <u>Explicit first stage Singly-Diagonally</u>
   Implicit Runge-Kutta
  - Stiffly accurate
  - Second-order stage accuracy
  - FSAL First is the Same As Last

$c_1 = 0$	0	0	0		0	0
$c_2$	$a_{21}$	$\lambda$	0		0	0
$c_3$	$a_{31}$	$a_{32}$	$\lambda$		0	0
: :	:	:	:	٠.	: :	•
$c_{s-1}$	$a_{(s-1)1}$	$a_{(s-1)2}$	$a_{(s-1)3}$		$\lambda$	0
$c_s = 1$	$b_1$	$b_2$	$b_3$		$b_{s-1}$	$\lambda$
	$b_1$	$b_2$	$b_3$		$b_{s-1}$	$\lambda$
	$\hat{b}_1$	$\hat{b}_2$	$\hat{b}_3$		$\hat{b}_{s-1}$	$\hat{b}_s$



### ESDIRK3 and 4



0	0	0	0	0
$\frac{1767732205903}{2027836641118}$	$\frac{1767732205903}{4055673282236}$	$\frac{1767732205903}{4055673282236}$	0	0
$\frac{3}{5}$	$\frac{2746238789719}{10658868560708}$	$-\frac{640167445237}{6845629431997}$	$\frac{1767732205903}{4055673282236}$	0
1	$\frac{1471266399579}{7840856788654}$	$-\frac{4482444167858}{7529755066697}$	$\frac{11266239266428}{11593286722821}$	$\frac{1767732205903}{4055673282236}$
	$\frac{1471266399579}{7840856788654}$	$-\frac{4482444167858}{7529755066697}$	$\frac{11266239266428}{11593286722821}$	$\frac{1767732205903}{4055673282236}$

#### Implicit, Third-order ESDIRK3

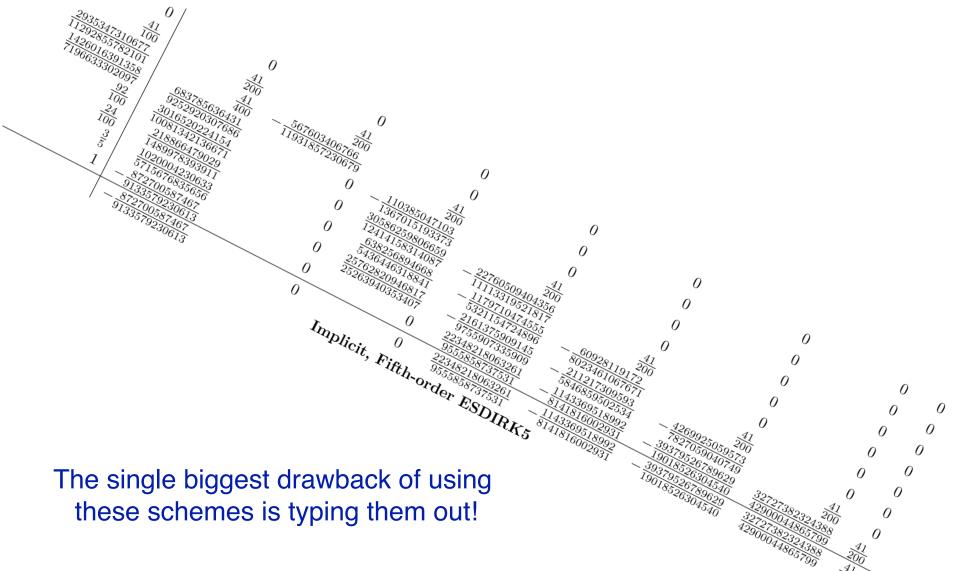
0	0	0	0	0	0	0
$\frac{1}{2}$	$\frac{1}{4}$	$\frac{1}{4}$	0	0	0	0
$\frac{83}{250}$	$\frac{8611}{62500}$	$-\frac{1743}{31250}$	$\frac{1}{4}$	0	0	0
$\frac{31}{50}$	$\frac{5012029}{34652500}$	$-\frac{654441}{2922500}$	$\frac{174375}{388108}$	$\frac{1}{4}$	0	0
$\frac{17}{20}$	$\frac{15267082809}{155376265600}$	$-\frac{71443401}{120774400}$	$\frac{730878875}{902184768}$	$\frac{2285395}{8070912}$	$\frac{1}{4}$	0
1	$\frac{82889}{524892}$	0	$\frac{15625}{83664}$	$\frac{69875}{102672}$	$-rac{2260}{8211}$	$\frac{1}{4}$
	$\frac{82889}{524892}$	0	$\frac{15625}{83664}$	$\frac{69875}{102672}$	$-\frac{2260}{8211}$	$\frac{1}{4}$

#### Implicit, Fourth-order ESDIRK4



### **ESDIRK5**







### **Von Neumann Analysis**

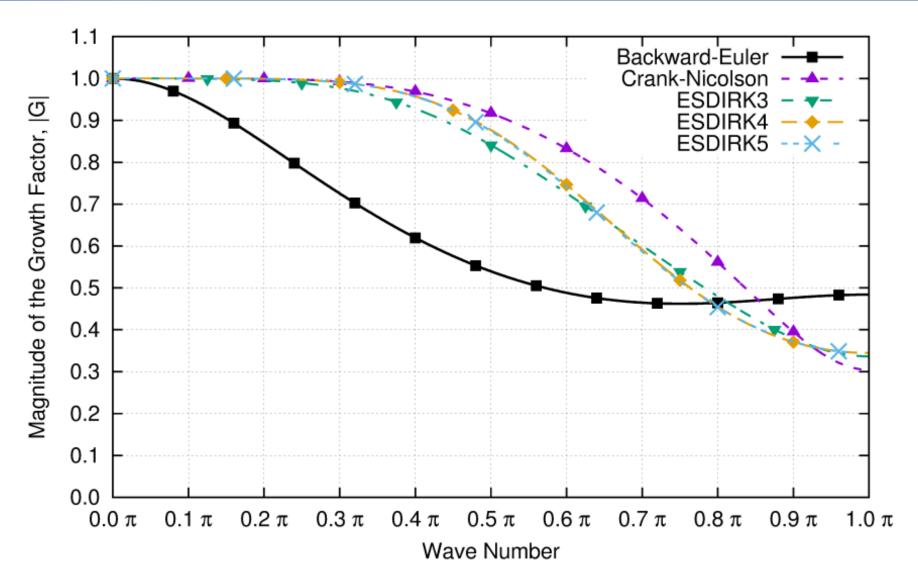


- Often used to study stability of schemes
- Von Neumann analysis is used to compare schemes for accuracy
  - Dissipation error
  - Dispersion error
- Assumes linear, periodic problems
- VNA theory and more results are in the associated paper



### Dissipation, CFL = 1.0

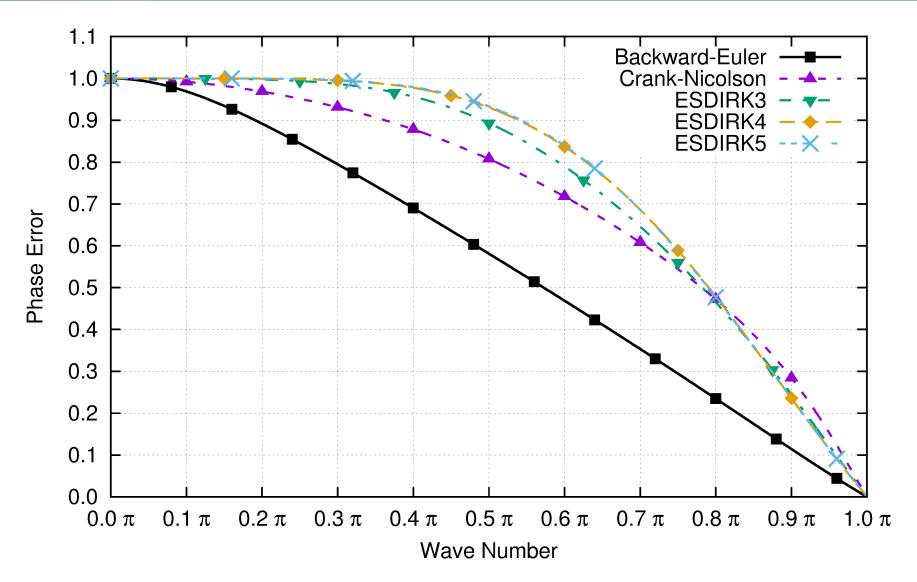






## Dispersion, CFL = 1.0

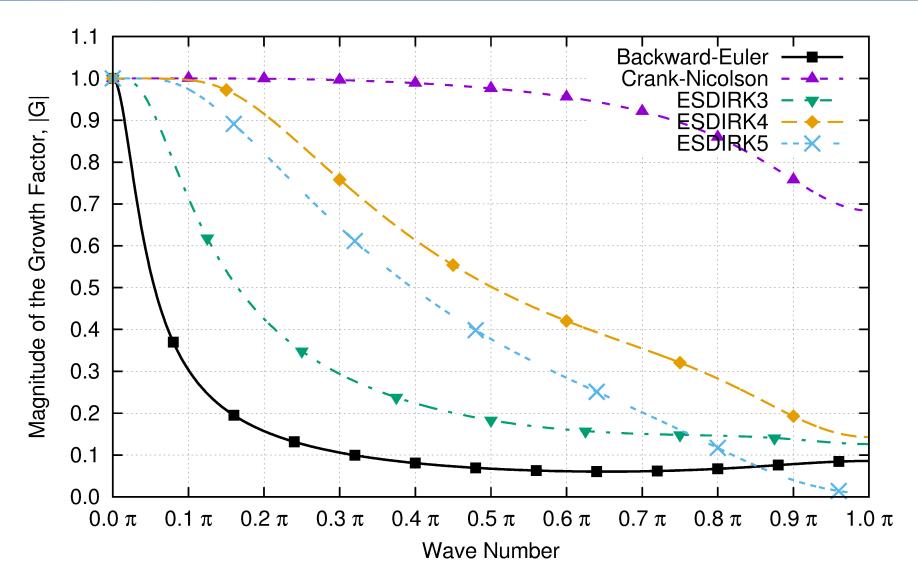






# Dissipation, CFL = 10.0

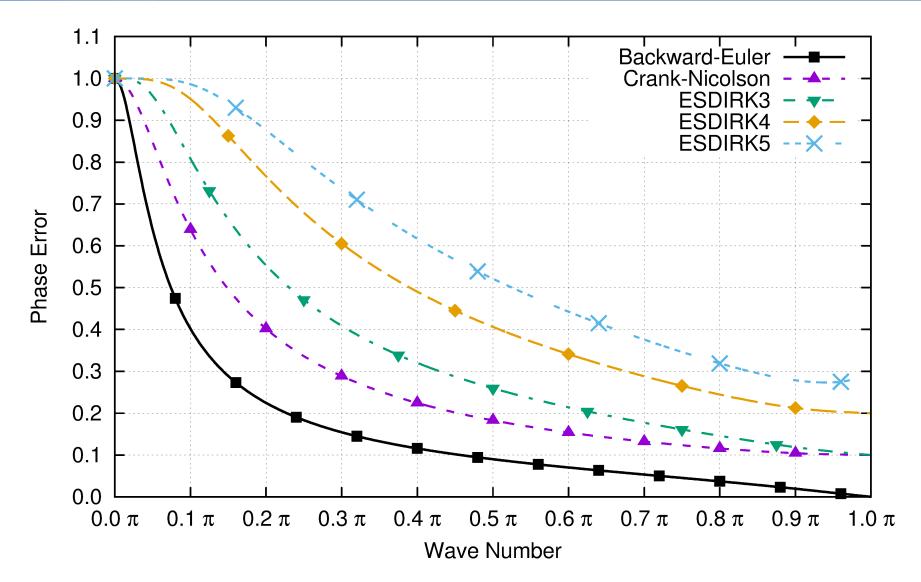






# Dispersion, CFL = 10.0







### 1-D Acoustic Wave



#### Unperturbed Mach number of 0.5

$$\rho_{\infty} = 8.7077 \times 10^{-1} \frac{kg}{m^3}$$

$$\rho u_{\infty} = 1.7458 \times 10^2 \frac{kg}{m^2 \cdot s}$$

$$T_{\infty} = 400K$$

$$R_{\infty} = 2.871 \times 10^2 \frac{J}{kg \cdot K}$$

$$\gamma = 1.4$$

Perturbation wave - 20 points per wave resolution

$$Q_o = Q_{\infty} + M\delta \hat{Q}_{u,u\pm c}$$

$$\delta \hat{Q}_{u,u\pm c} = \hat{\delta} \cdot \cos(kx)$$
where  $\hat{\delta} = 0.01$ 

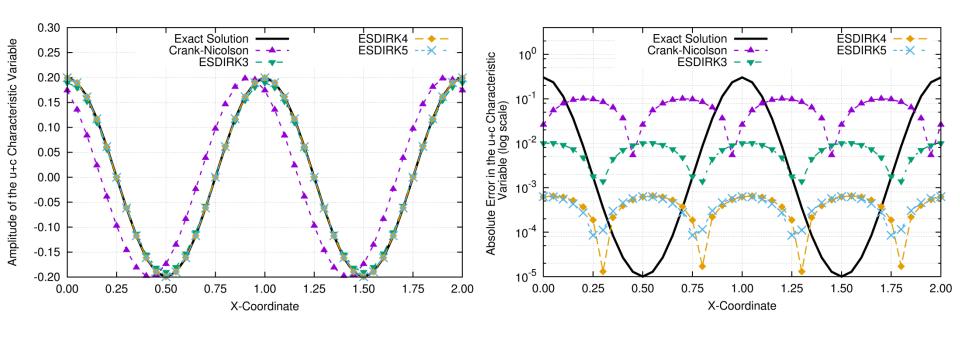
More results in the paper



# 1-D, *CFL* = *1.0*, 10 Periods



	Dissipation Error		Dispersion Error	
Scheme	VNA	Simulation	VNA	Simulation
Crank-N-colson	$3.05 \times 10^{-3}$	$1.00 \times 10^{-2}$	$8.11 \times 10^{-2}$	$8.11 \times 10^{-2}$
ESDIRK3	$5.02 \times 10^{-2}$	$5.02 \times 10^{-2}$	$1.51 \times 10^{-3}$	$1.53 \times 10^{-3}$
ESDIRK4	$3.13 \times 10^{-3}$	$3.13 \times 10^{-3}$	$1.50 \times 10^{-4}$	$1.58 \times 10^{-4}$
ESDIRK5	$3.14 \times 10^{-3}$	$3.14 \times 10^{-3}$	$6.78 \times 10^{-5}$	$6.90 \times 10^{-5}$

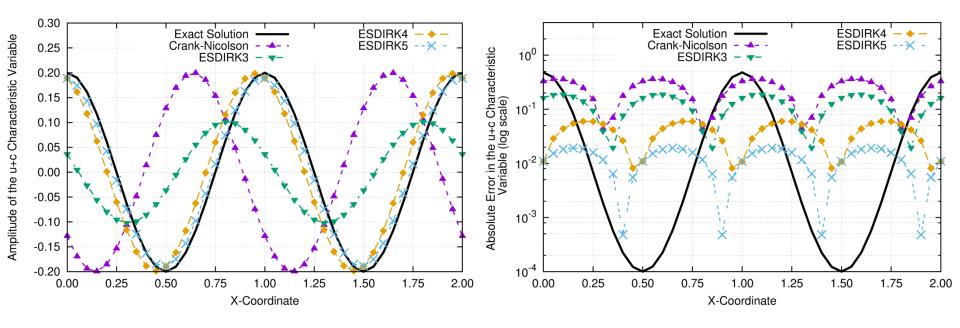




## 1-D, CFL = 10.0, 1 Period



	Dissipati	on Error	Dispersion Error	
Scheme	VNA	Simulation	VNA	Simulation
Crank-Nicolson	$9.02 \times 10^{-5}$	$2.44 \times 10^{-3}$	$3.61 \times 10^{-1}$	$3.61 \times 10^{-1}$
ESDIRK3	$4.99 \times 10^{-1}$	$4.90 \times 10^{-1}$	$1.92 \times 10^{-1}$	$1.92 \times 10^{-1}$
ESDIRK4	$7.22 \times 10^{-3}$	$7.25 \times 10^{-3}$	$4.90 \times 10^{-2}$	$4.90 \times 10^{-2}$
ESDIRK5	$5.10 \times 10^{-2}$	$5.46 \times 10^{-2}$	$1.38 \times 10^{-2}$	$1.39 \times 10^{-2}$

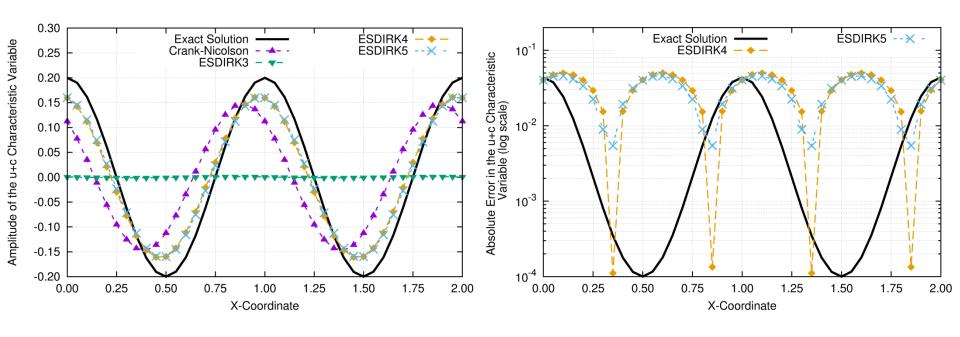




# 1-D, *CFL* = *1.0*, 1000 Periods



	Dissipati	on Error	Dispersion Error	
Scheme	VNA	Simulation	VNA	Simulation
Crank-Nicolson	$2.63 \times 10^{-1}$	$2.65 \times 10^{-1}$	$8.11 \times 10^{0}$	$8.10 \times 10^{0}$
ESDIRK3	$9.94 \times 10^{-1}$	$9.94 \times 10^{-1}$	$1.51 \times 10^{-1}$	$1.00 \times 10^{-1}$
ESDIRK4	$2.69 \times 10^{-1}$	$1.95 \times 10^{-1}$	$1.50 \times 10^{-2}$	$3.00 \times 10^{-2}$
ESDIRK5	$2.70 \times 10^{-1}$	$2.01 \times 10^{-1}$	$6.78 \times 10^{-3}$	$2.50 \times 10^{-2}$





# 3-D Isentropic Vortex



#### Free-stream Mach number of 0.5

$$\rho_{\infty} = 1.0 \frac{kg}{m^3}, \quad \rho u_{\infty} = 200.0 \frac{kg}{m^2 \cdot s}, \quad \rho v_{\infty} = 0.0 \frac{kg}{m^2 \cdot s}, \quad \rho w_{\infty} = 0.0 \frac{kg}{m^2 \cdot s}, \quad \rho e_{0,\infty} = 305714.3 \frac{kg}{m \cdot s^2}$$

$$R_{\infty} = 287.11 \frac{J}{kg \cdot K} \text{ and } \gamma = 1.4$$

#### Perturbation - 11 points across the vortex

$$\delta u = -\sqrt{R_{\infty}T_{\infty}} \frac{\alpha}{2\pi} (y - y_0) e^{\phi(1 - r^2)}$$

$$\delta v = \sqrt{R_{\infty}T_{\infty}} \frac{\alpha}{2\pi} (x - x_0) e^{\phi(1 - r^2)}$$

$$\delta T = T_{\infty} \frac{\alpha^2 (\gamma - 1)}{16\phi \gamma \pi^2} e^{2\phi(1 - r^2)}$$

More results in the paper

$$\alpha = 4 \text{ and } \phi = 1$$
Vortex center:  $(x_0, y_0)$ 

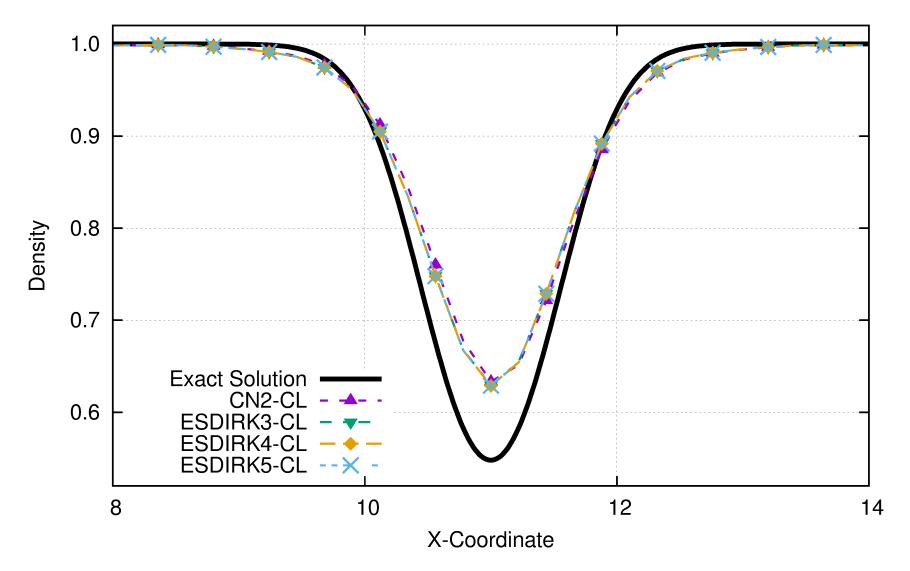
$$r = \sqrt{(x - x_0)^2 + (y - y_0)^2}$$





# 3-D, *CFL* = 1.0, 40 Lengths, 11 Points Across the Vortex

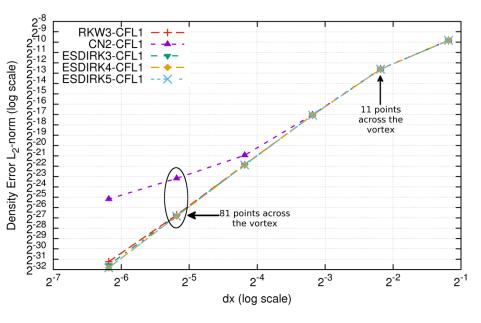


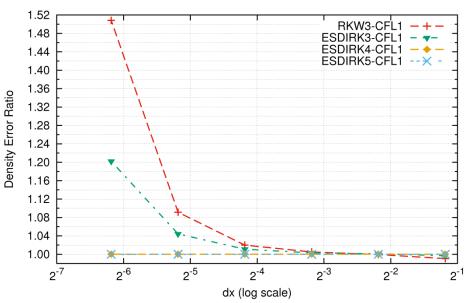




# 3-D, *CFL* = 1.0 Different Resolutions



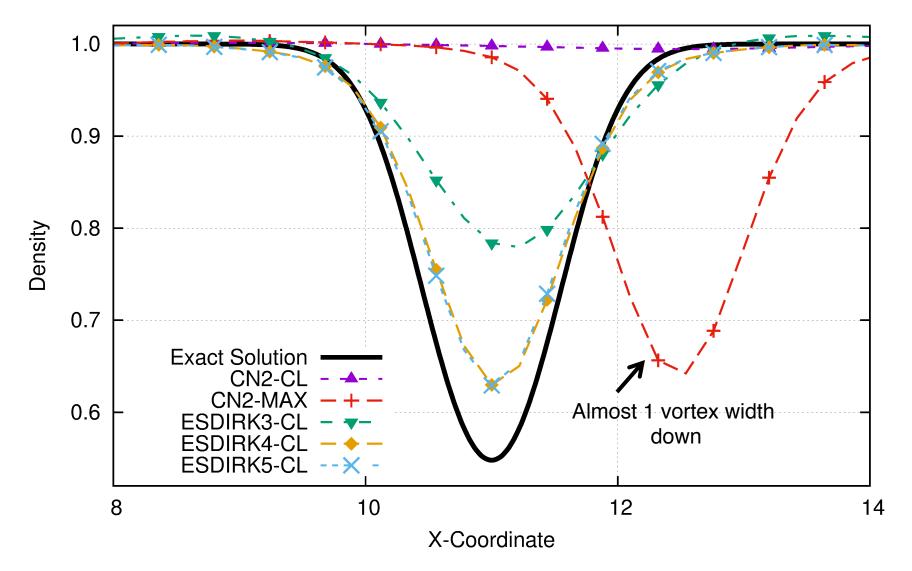






### 3-D, *CFL* = 8.0, 40 Lengths, 11 Points Across the Vortex

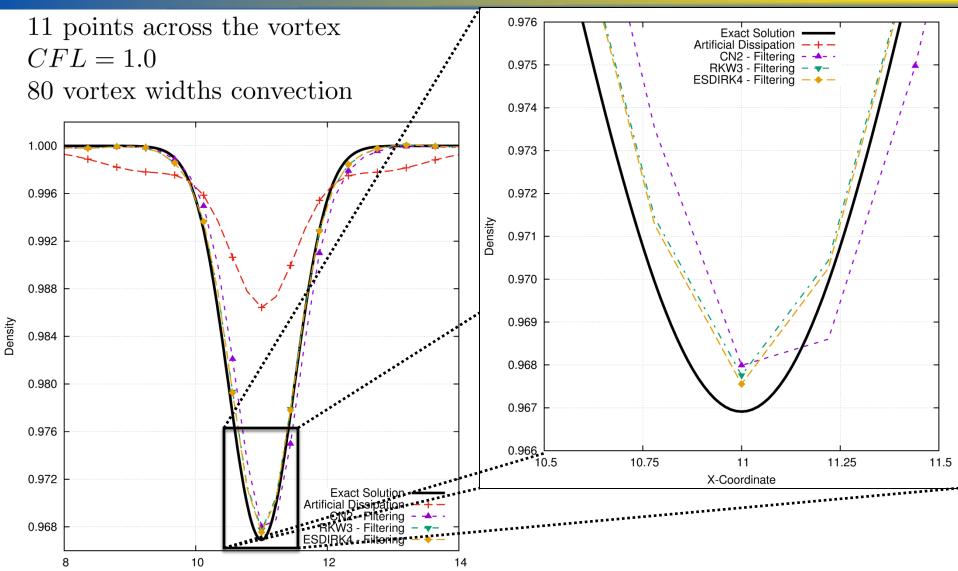






# **Sneak Peak: Filtering**





X-Coordinate



### Conclusions



- 2<sup>nd</sup>- and 3<sup>rd</sup>-order time integrators for 5<sup>th</sup>-order spatial schemes are inadequate
  - The same order of spatial and temporal discretizations is preferable
  - However, ESDIRK5 is not much better than ESDIRK4
    - 7 implicit stages vs. 5 implicit stages
- Higher-order time integrators:
  - Do not show significant improvement on coarse grids at CFL of one
  - Are better at high CFL number
  - Are better on highly refined grids
- Spatial error usually dominates for typical CFL numbers and grid resolutions
  - Central difference plus artificial dissipation schemes are inadequate



### **Future Work**

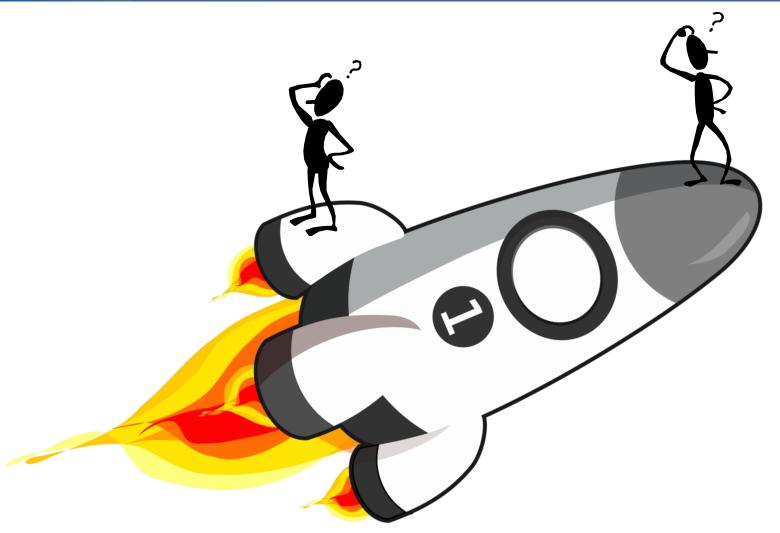


- Implement more accurate spatial schemes of the same orders of accuracy
  - Compact-difference schemes
  - Filtering schemes
- Derive better ESDIRK schemes tailored to the desired dissipation and dispersion properties
- Add preconditioning to take maximum advantage of the ESDIRK time integrators for stiff problems
  - Improved convergence efficiency
  - Improved solution accuracy



# Questions???







# **Extra Slides**





# 3-D, *CFL* = 8.0 Different Resolutions



